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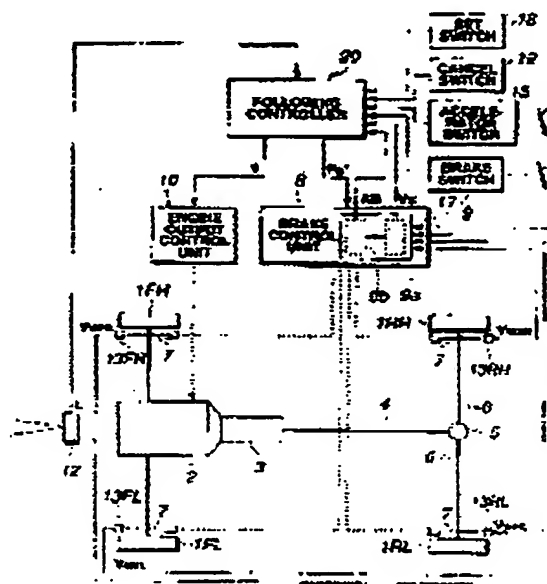
**Preceding vehicle following control system**

(EP1070624)

**Folgevorrichtung für vorausfahrende Fahrzeuge**

(EP1070624)

Actual vehicle speed ( $V_s$ ) and actual vehicle spacing ( $L$ ), between the controlled vehicle and a preceding vehicle, are sensed and a driving/braking force acting on the controlled vehicle are regulated. A controller controls the speed ( $V_s$ ) or the spacing ( $L$ ) in a following control mode (FM) and changes to a deceleration control mode (DM) if anti-lock brake control is started in the following control mode (FM). The controller cancels deceleration control when the spacing ( $L$ ) becomes greater than a predetermined value ( $L_0$ ). <IMAGE>



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